Integrated Mission Operation Concepts for the Dream Chaser® Cargo System

Jason Gabbert – Sierra Nevada Corporation Madeline Devereaux – Sierra Nevada Corporation Jeremy Owen – Sierra Nevada Corporation David Kortenkamp – TRACLabs Inc. Scott Bell – TRACLabs Inc. Gilles Kbidy – L3Harris

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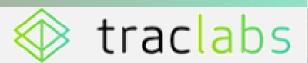
Cargo System

Sierra Nevada Corporation's (SNC) Space Systems is leading an effort to create a low-cost space system to support the transport of cargo to and from low-Earth orbit, including the ISS. This effort called the Dream Chaser Program is focused on the development of the Dream Chaser Cargo System.

The Dream Chaser Cargo System consists of the uncrewed Dream Chaser and Cargo Module. The Dream Chaser is a reusable, autonomous, lifting-body spaceplane that launches vertically on top of a launch vehicle and lands horizontally on a conventional runway. The Cargo Module is an expendable element that attaches to the Dream Chaser to carry cargo and is jettisoned for atmospheric burnup prior to entry.







Credit: Sierra Nevada Corporation

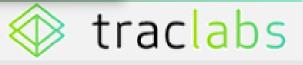
Dream Chaser Cargo System ConOps

Link

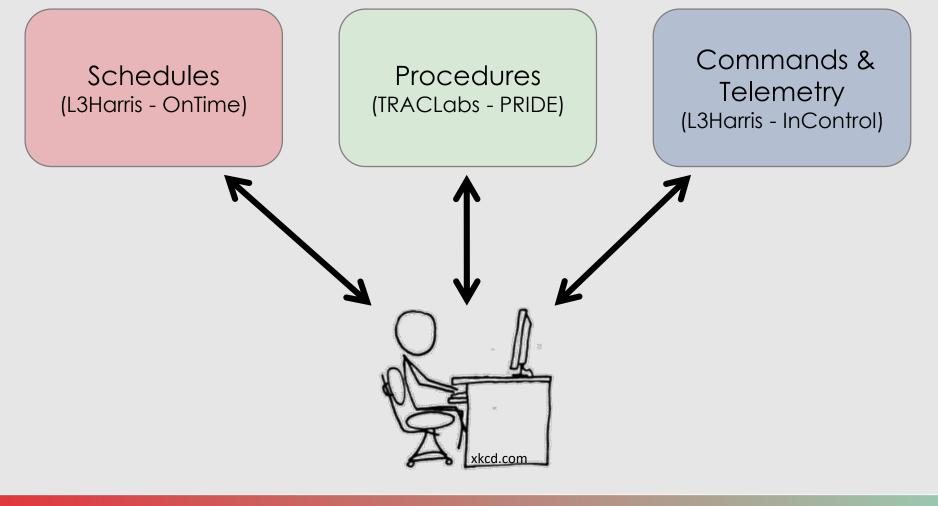






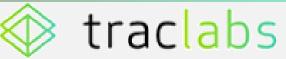


Typical Spacecraft Operations

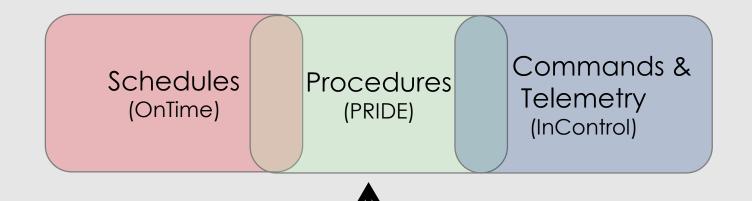


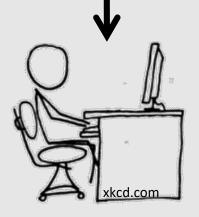






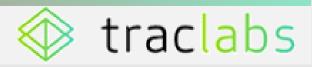
Our Spacecraft Operations



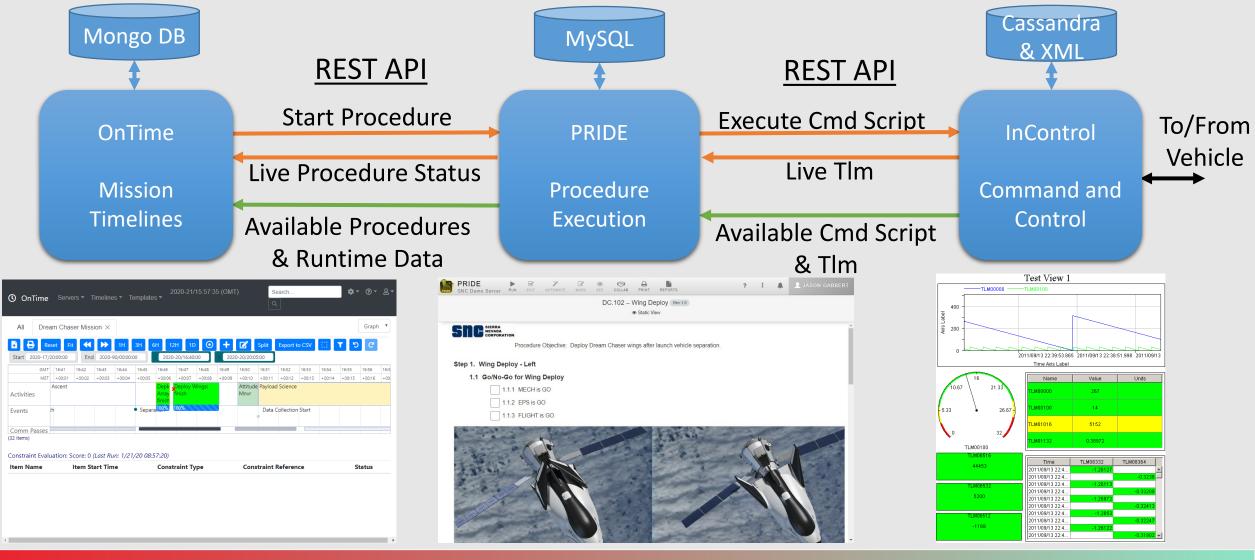






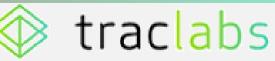


Architecture & Connectivity









Mission Planning & Scheduling with OnTime

- Distributed, collaborative mission planning and scheduling
 - Cloud-native (public or on premises), Web UI and REST interfaces
 - Live concurrent editing across sites and users
 - Back-end storage is fault tolerant and distributed
- Integrated with multiple procedure execution and command and control systems
- Real-time constraint checking, conflict resolution and AI algorithms to optimize schedule allocation

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Electronic Procedures using PRIDE

PRIDE

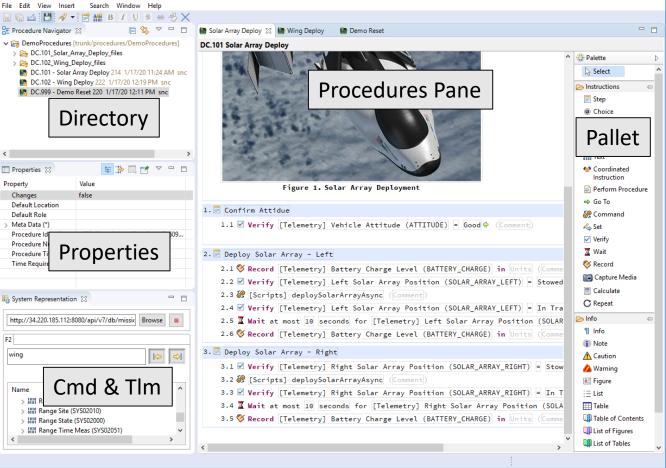
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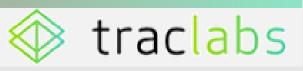
- Drag-and-drop authoring
- Automatic formatting
- Server-based, collaborative procedure execution system
- Multiple operators can interact with the same procedure
- Integrated telemetry and commanding
- Back-end database stores as-run procedure data
- Automation capabilities

PRIDE Author Search Window









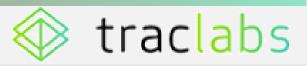
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| | GMT | 16:40 | 16:41 | 16:42 | 16:43 | 16:44 | 16:45 | 16:46 | 16:47 | 16:48 | 16:49 | 16:50 | 16:51 | 16:52 | 16:53 | 16:54 | 16:55 | 16:56 | 16:57 | 16:5 |
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Current Time









When time bar reaches an automated activity, a PRIDE procedure is started:

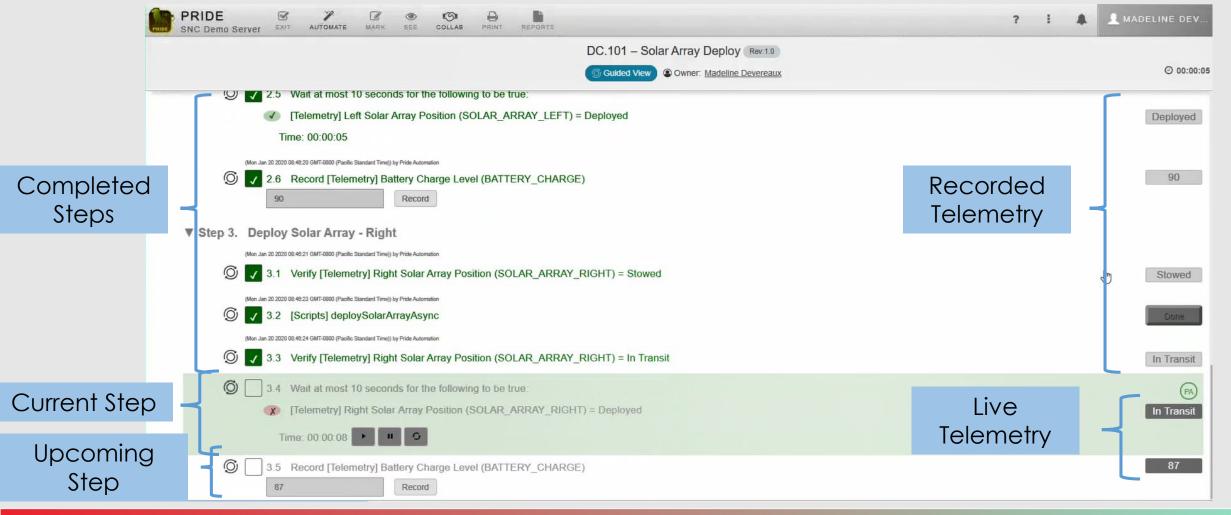
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| | ly confirm spacecraft is in proper attitude and then deploy the arrays. | |
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| This activity should be performed ASAP to ensure power generation. | | |
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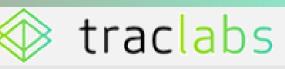


Procedure runs automatically, sending commands and verifying telemetry







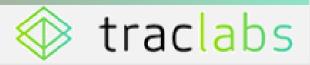


When procedure is complete, status updates on timeline

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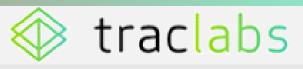


Procedures can also have manual steps requiring user input between automation

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Activity Analysis and Metrics

- As-run procedure database contains
 - all operator interactions
 - all telemetry used to make procedure decisions
 - timestamps for all instructions
- Machine learning algorithm estimates time-to-complete for each procedure from current instruction
- Metrics available via API for feedback into scheduling

| Wing Dep | oy Summ | ary | | | | | | | | | | |
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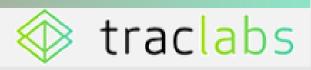


Summary

- We have developed a seamless operator interface between the main flight execution tools featuring:
 - Automatic standards enforcement
 - Collaborative real-time execution
 - Data sharing
- Building flexibility into ground system tools through REST API enables creative integration
 - Optimizing operator actions
 - Interfacing between different providers
 - Ability to adopt evolving best practices in space systems command and control







Questions



Jason Gabbert – Sierra Nevada Corporation Madeline Devereaux – Sierra Nevada Corporation Jeremy Owen – Sierra Nevada Corporation David Kortenkamp – TRACLabs Inc. Scott Bell – TRACLabs Inc. Gilles Kbidy – L3Harris

