The On-Demand, Information-Driven Satellite Control Network

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Why On Demand and Info Driven?

- Responsive Automated Services to smaller missions¹
- Flexible services¹
- Demand access based on event event-driven demand
- Enables missions to rapidly re-point instruments for observation of cosmic and earth-based events¹
- Supports SV 911 initiative
- Supports availability, continuity of ops and mission assurance



Aspects and Capabilities for On Demand

- Global coverage
- Multiple contact/multiple access
- Supports all aspects of TT&C
- Supports all users LEOs, MEOs, HEOs
- Supports all mission phases: launch, early orbit, anomaly resolution and on-station
- Guarantees availability of resources
- Mission assurance -- all mission phases



Aspects and Capabilities of On Demand

- Based on service-oriented architecture (SOA)
- Provides tiered views for monitoring, service execution, FDFI, performance and condition monitoring — app based
- Provides multiple tracking –all mission phases
- BEM –reduce contact time
- Exploits satellite house keeping



 Directive driven—match contact type/support to satellite activity blocks (SABs)



Supports SV 911 initiative



Aspects/Capabilities of Information Driven*

- Tiered view of system
 - Network
 - Site
 - Functionality/thread
 - Subsystem /LRU
 - LRU/book/panel
- Provides of view environment
 - Threats/situation awareness
- Provides analytics



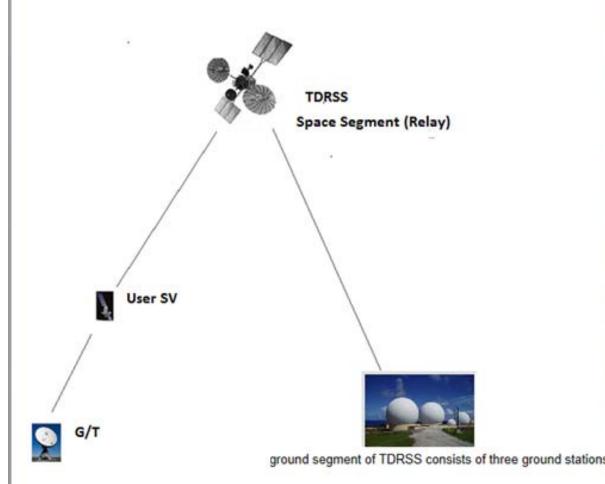
^{*}Supports continuity of ops, availability, mission assurance

Information/Knowledge

- Health— overall, to LRUs (DSPs), subsystems books, includes currents, temps (standard, mean)
- Performance—during support/contacts
 - Includes all TT&C (ranging, Doppler, TLM, etc.)
- Configuration and status —upon change
- Self test off-line and online
- Situational awareness
- Analytics
- Trending/comparative analysis/recognition
- Across networks (if interoperable)



Present architectures –TDRSS n AFSCN



Present		
Capabilities	AFSCN	TDRSS
		CDMA/
Multiple	12070	Spread
Access	FDM	Spectrum
Multiple		
Contact	No	MA/BFN
SOA	ESD	SGSS
Tiered		
Architecture	RBC	NO
	RBC not	
CBM+	Deployed	No
Accountabilit	Limited by	
У	interface	Not Tracking
Global	No-	Yes -for SV
Coverage	Terrestrial	above
Information		
Driven	No	No
SOA		
Scheduling &		
Planning	Yes	Yes
Multiple		
Contact		
Tracking	No	No
Арр		
Capability	RBC	No
On Demand		
Access	No	DAS





Present architectures (summary)

- Terrestrial systems SA parabolic dishes
- Prior user scheduling and network coordination—works for fewer larger SV
- Not bandwidth efficient modulation (BEM) or spectrally efficient
- Maintenance is reactive or corrective
- Data intensive archive everything
- Tracl
 - Tracking –not low signal; Σ to Δ



Building Towards On-Demand

SEGMENT ALLOCATION	CAPABILITY	ARCHITECTURE
	Coverage	Site location /SV spatial range
	Directivity	Site/SV knowledge
	Multiple contact	Antenna type n number of antenna
LINK	Spectrum	Based on allocation
	Segmentation	Based on allocation
	Spectrum access	Multiplexing (FDM, CDMA, TDMA)
	Contact duration	Modulation - BEM/SV house keeping
	Tracking-all phases	Low signal tracking
	EIRP- all phases	Antenna design/type
	Availability of service	FDFI, CBM+ , app design
	Capacity design	# Of mission(s)/mission types requirement

Building Toward On-Demand

	SCHEDULING	SOA/KNOWLEDGE/AUTOMATED/GUI/APP
Network Cntl	Availability of network	FDFI, CBM+
	Flexible/event driven	Directive driven via MOC
	Cross-network	Interoperability
	911 event-driven	SV based directivepreamble/routing info
	Analytics	Trendingusage/ types

	CONTACT DURATION	SV HOUSEKEEPING / MISSION PHASE/BEM
SV/User	Directive-based	SABsfor MVRS, OBC, TLM, science/ mission
	911 event-driven	Preamble Site/MOC directives



TDRSS DAS and AFSN GDPAA insertion*

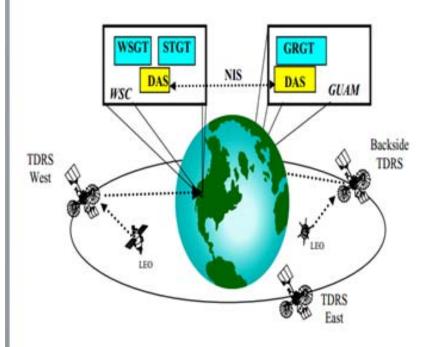
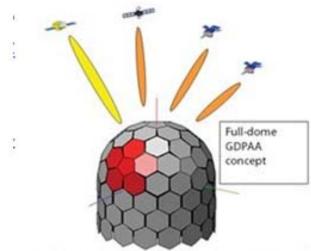


Figure 1: NASA Space Network and DAS



The Geodesic Dome Phased-Array Antenna Advanced Technology Demonstration proved the antenna's capacity to provide multiple, simultaneous, dual-band (L-band and S-band) contacts for telemetry, tracking, and command of Air Force Satellite Control Network satellites.

*A good start if exploited or implemented



Architectural Drivers

- Coverage— SV in view
- Tracking user/SV position location (ephemeris); low signal level
- Multiple contact antenna phased arrayed systems
- Multiple access waveforms
- Coordination alleviation (automation)
- SV 911 initiative
 - Directive driven based on SABS/contact type
 - Info based, CBM+, tiered FDFI



Types of Maintenance Programs

Two types of maintenance:

- 1. Reactive or corrective maintenance
- 2. Preventive maintenance

Preventive maintenance is divided into:

- Planned maintenance
- Condition-based or predictive maintenance



Summary

- Exploit SABs, SV housekeeping
- Reduce contact time (BEM, spectral efficiency)
- Increase capacity (multiple contact/multiple access)
- Develop low signal detect tracking (find/detect SV 911 call)
- Develop MA/BFN scanning to detect 911 call
- Develop tiered views for FDFI and CBM+
- Provide trending/analysis and analytics (cloud)
- Store information not data (cloud)
- Recognize dedicated demand missions



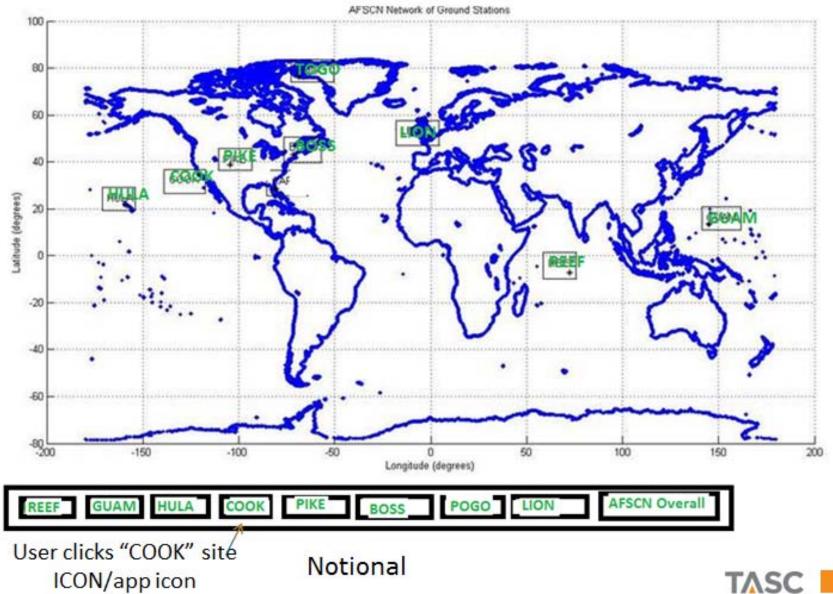
Info Driven/Tiered Architecture -FDFI/ CBM+/Apps

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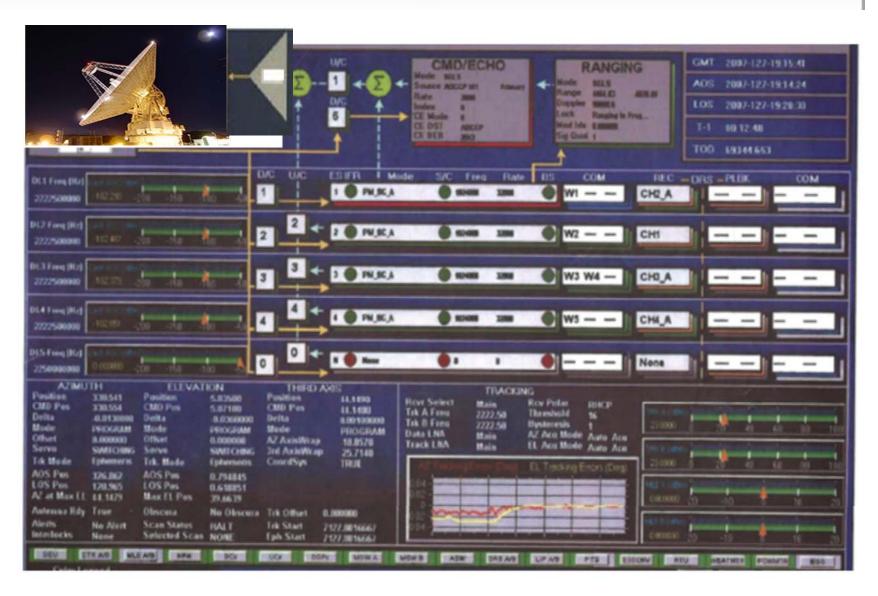
Back up charts



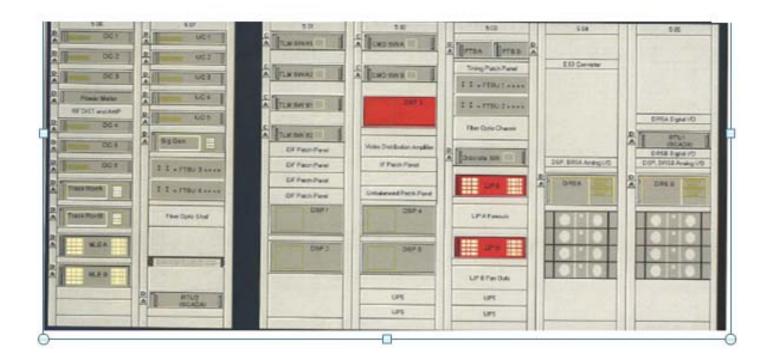
AFSCN (Top Tier) -- All Green

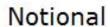


First Tier at Site – FDFI Summary Performance



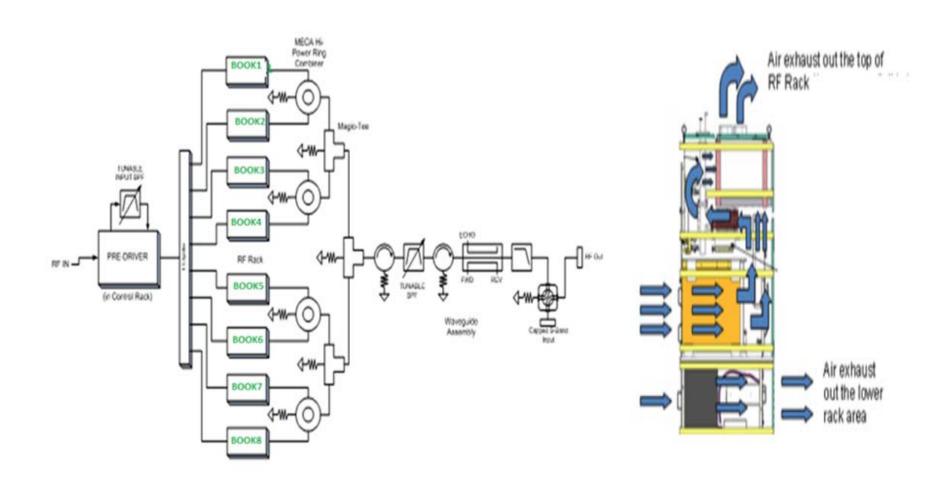
Second Tier FDFI – LRU





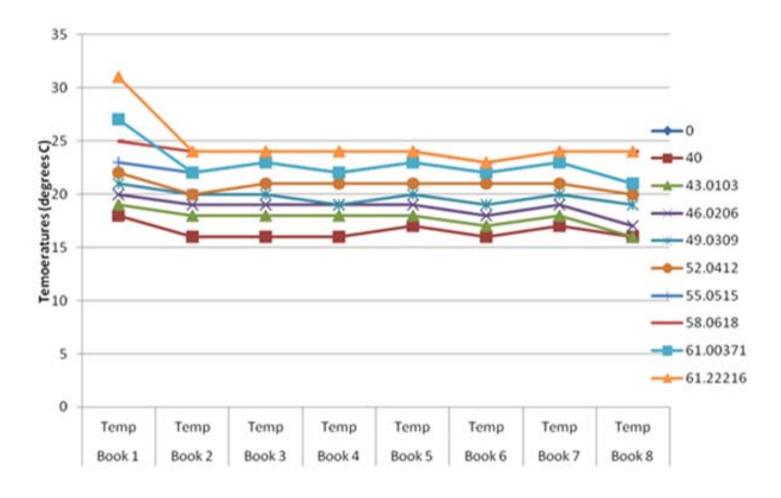


2nd Tier HPA Subsystem – RF Combining



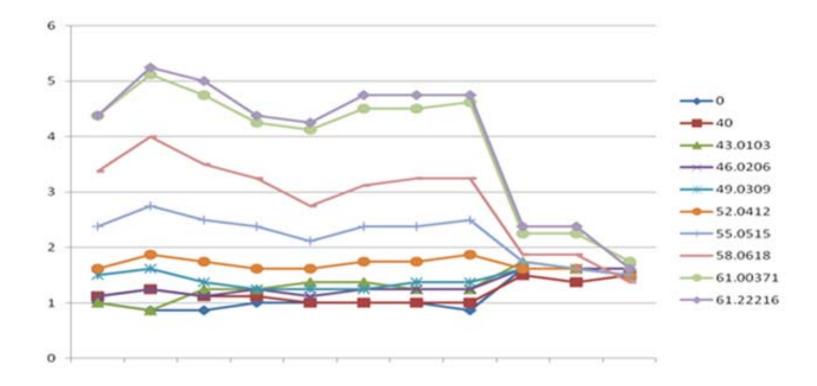


Book Temperatures vs Total Output Power





Internal Book Currents vs Total Power





G/T types of Information

RTS types of information (data)

- FDFI information
- Performance data- real-time data during SV contact
- Configuration/status data upon change
- Health preprocessed data
- Long-term trending data processed data at site



References

- "THE NASA SPACE NETWORK DEMAND ACCESS SYSTEM (DAS)," Thomas A. Gitlin (NASA GSFC), Walter Kearns & William D. Horne (ITT Industries), Space Ops, 2002
- "Inserting the GDPAA into the AFSCN," Unpublished Aerospace TOR, Bruno J. Calanche, December 2004
- "Advanced Ephemeris Update Receiver" Air Force SBIR, Bruno <u>Calanche</u> and Capt . Joe <u>Spagnolia</u>, <u>Vinay Swimanathan</u> 2011
- "RTS Performance Monitoring (RPM) Guidance for Prototype
 Development," Bruno <u>Calanche</u> ,Capt. Joe <u>Spagnolia</u>, <u>Vinay Swimanathan</u>,
 2010
- 5) "Condition Monitoring of a High-Power Amplifier Subsystem based on RF Combining using a Built in Self-Test and Performance Templates," Bruno Calanche, unpublished technical memo, Feb. 18, 2012—possible submission to IEEE



