

Indefinitely Evolvable Architectures: Event-Based Systems

Ted Faison

Faison Computing Inc.

ted.faison@computer.org

EBSs have Superior Non-Functional Characteristics

- **Manageability** - Independent teams
- **Maintainability** – Independent changes
- **Deployability** – Independent updates
- **Testability** – Independent parts
- **Verifiability** – Independent implementations
- **Flexibility** – Independent designs

EBSs are cheaper and faster to build

- EBSs are cheaper

Lots of small and independent parts are cheaper to build than fewer large and dependent parts

- EBSs are easier to build

Development teams can work largely in parallel, due to the independence between parts. Final integration is much easier.

- EBSs can evolve indefinitely

The parts are small and independent, so changes in the system requirements tend to have much smaller impacts on the individual parts. Changes often require only changing the system wiring and adding new parts.

Important EBS Definitions

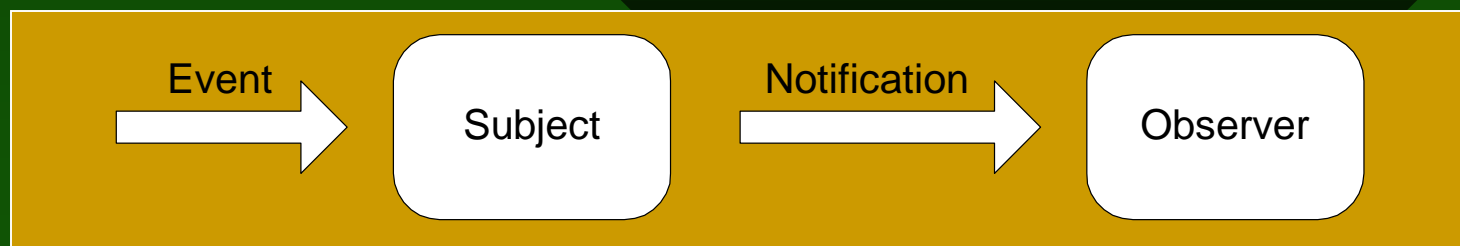
- Event

A detectable occurrence

- Notification

Messages triggered by events

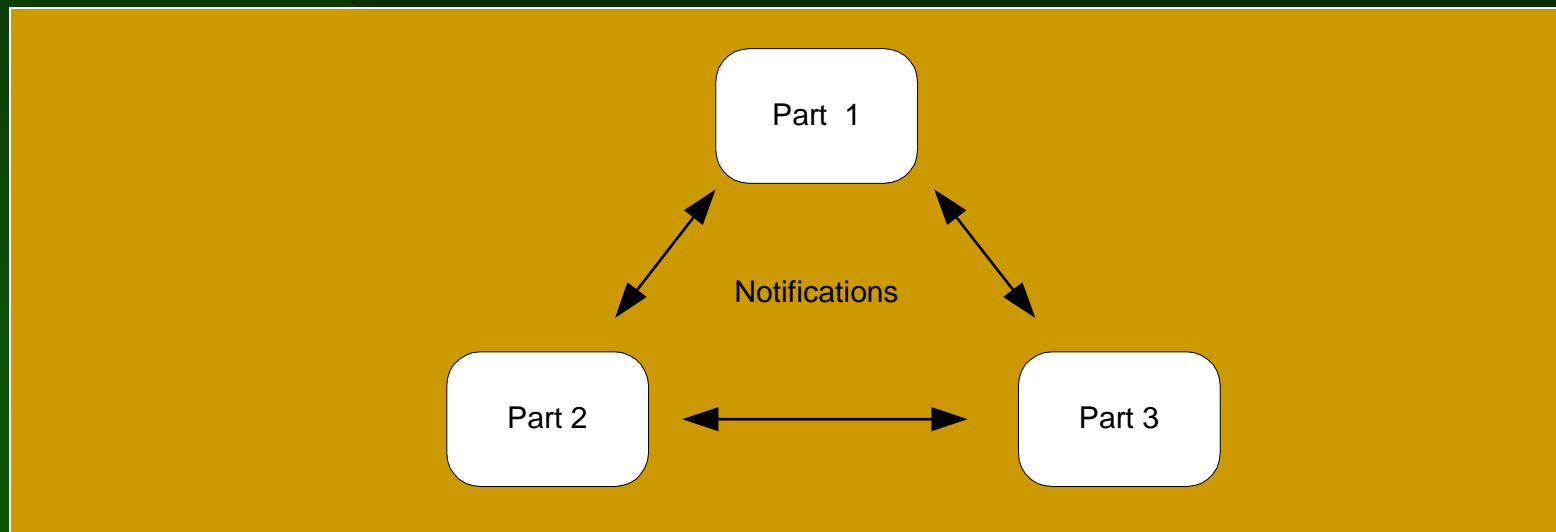
- The Observer design pattern



What is an EBS?

- It's all about the system connectivity

The constituent parts interact primarily or solely via notifications

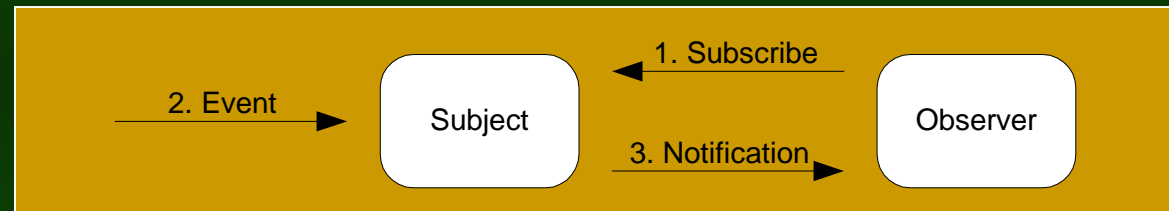


What is an EBS?

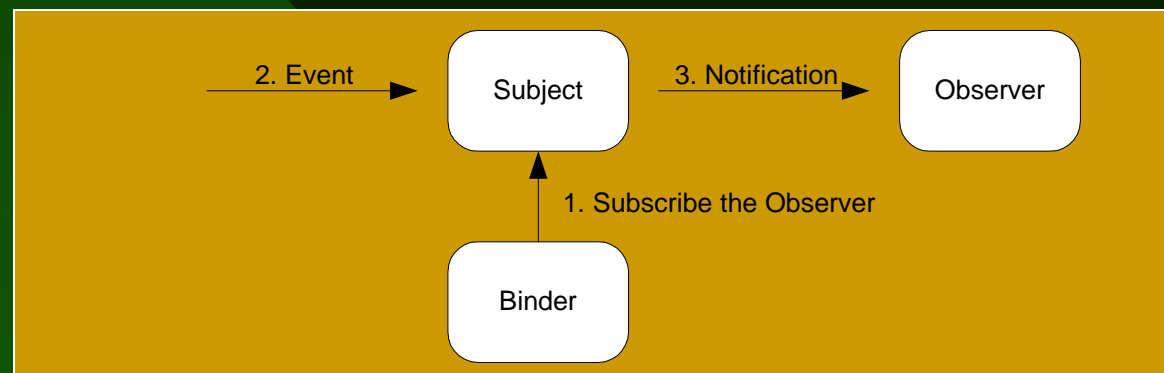
- It's all about coupling (and how to avoid it)
 - Static Coupling
 - Occurs at compile-time*
 - Greatly affects development teams*
 - Dynamic Coupling
 - Occurs at run-time*
 - Has little affect on development teams*

Improving the Observer pattern

- Self-subscribing Observers are coupled to Subjects



- Binders decouple the parts



Firing Events

(aka sending notifications)

- Sending Messages
- Using Procedure Calls

- Typed calls

Introduce type coupling, which is static

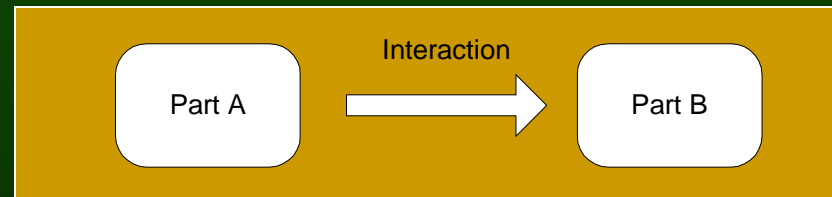
Example: myTypedReference.DoSomething()

- Untyped calls

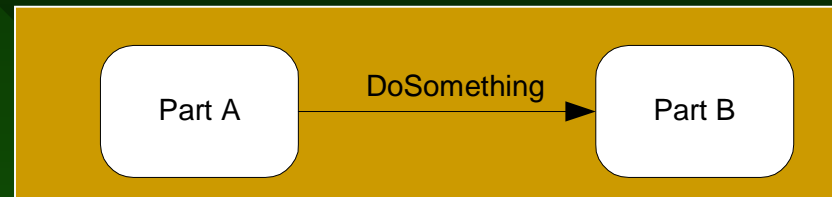
Introduce signature coupling, which is dynamic

Example : myMethodReference.Execute()

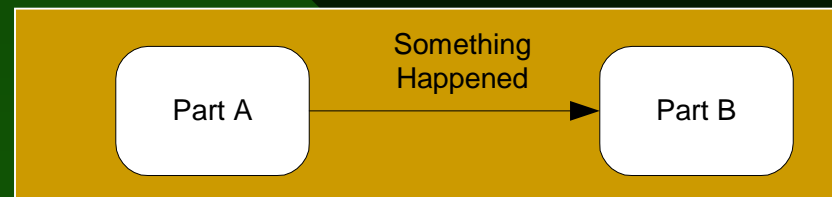
Interaction dynamics: active and reactive patterns



- Active interactions



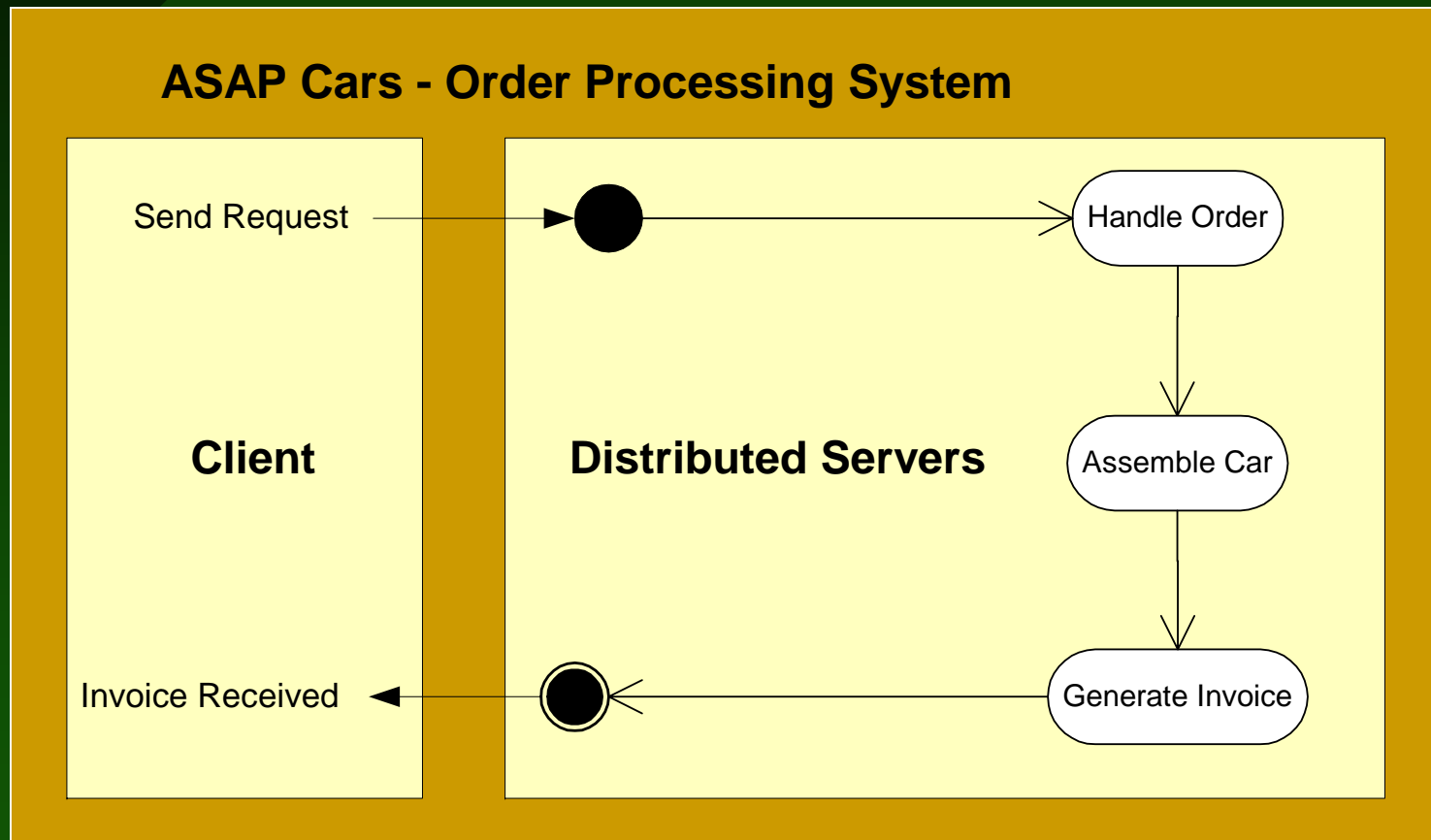
- Reactive interactions



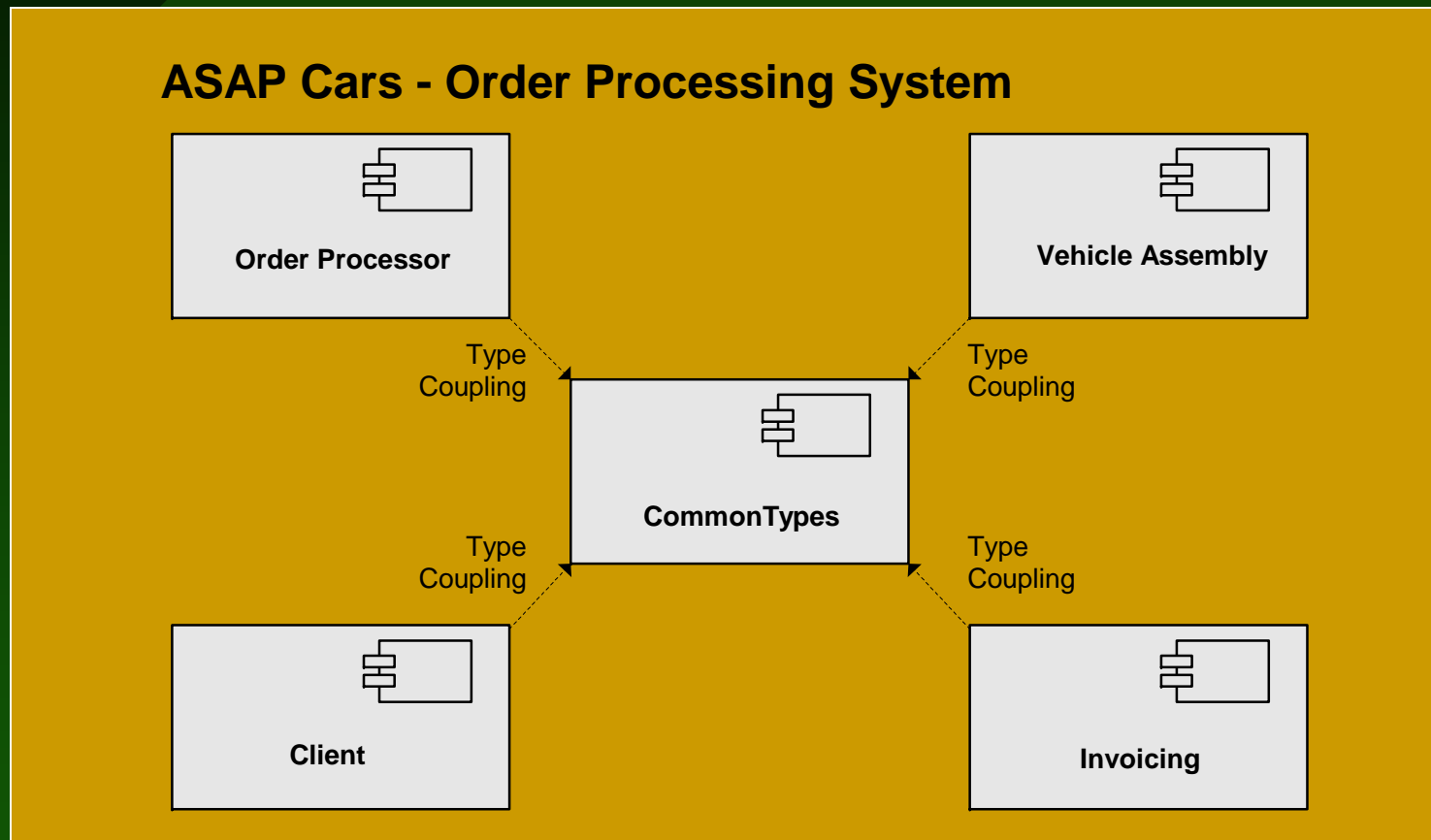
Complexity Versus Size

- Heavily coupled systems: complexity grows exponentially with size
- Decoupled systems: complexity grows linearly with size

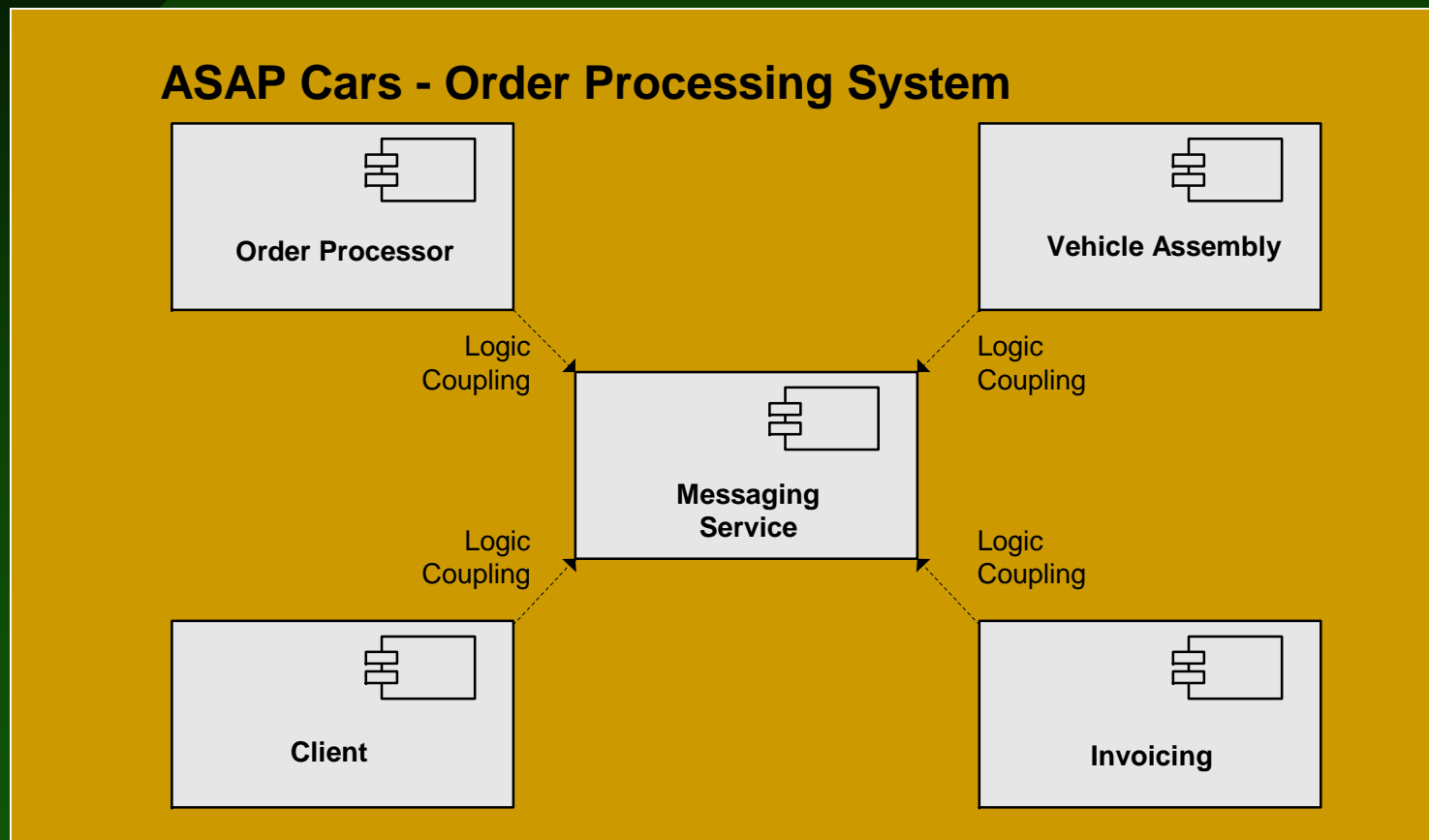
Case Study 1: A Distributed Workflow System



System Coupling Diagram

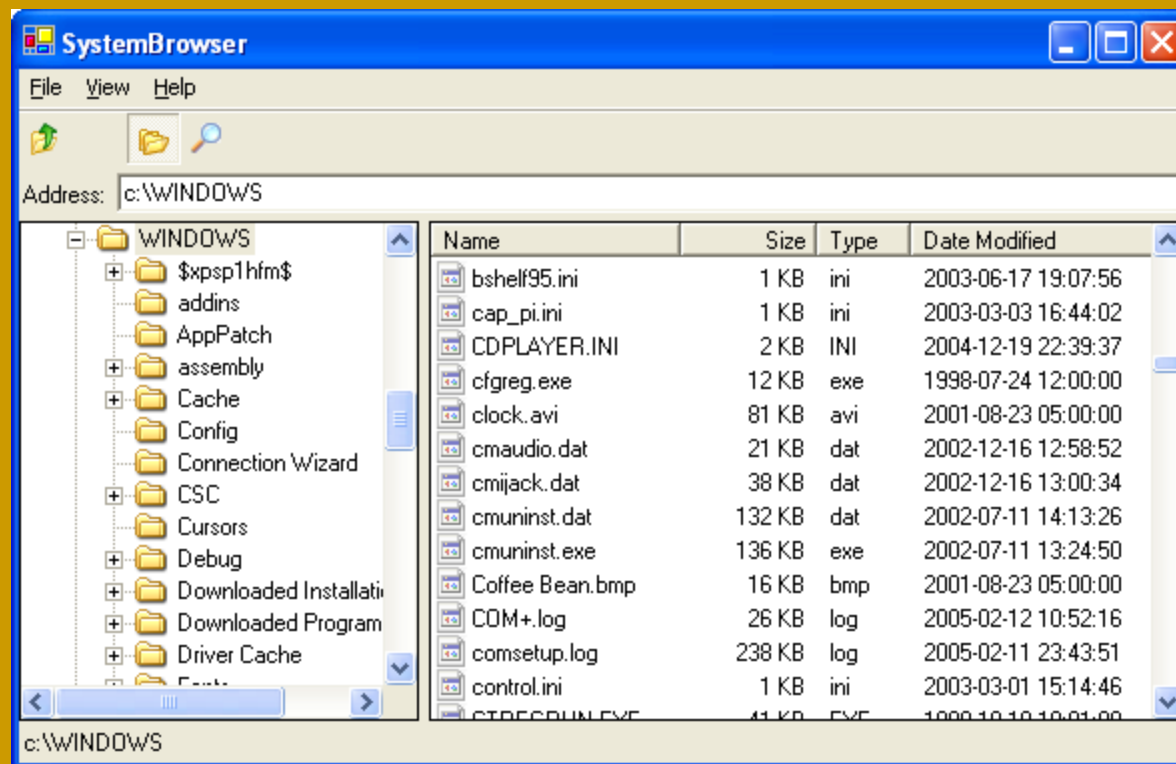


System Communication



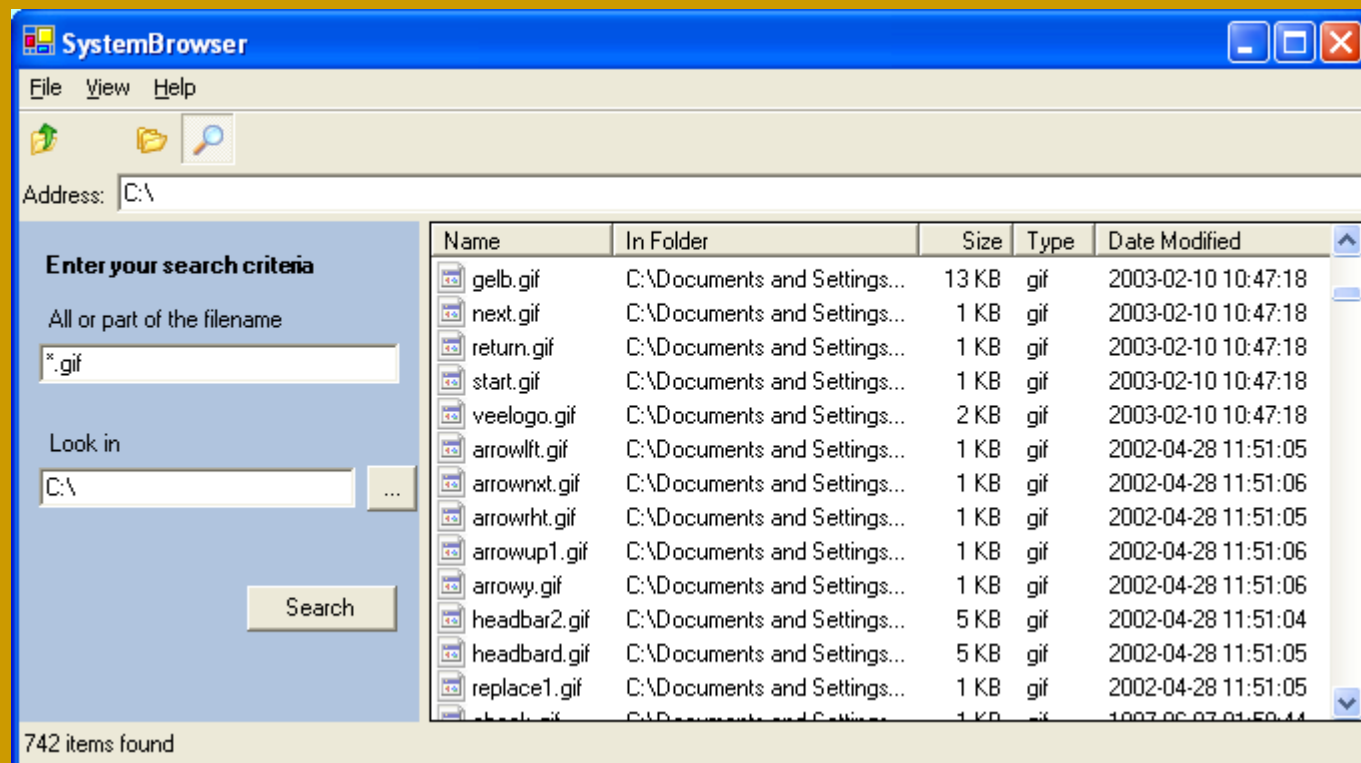
Case Study 2: A System Browser

User Interface - File Browser

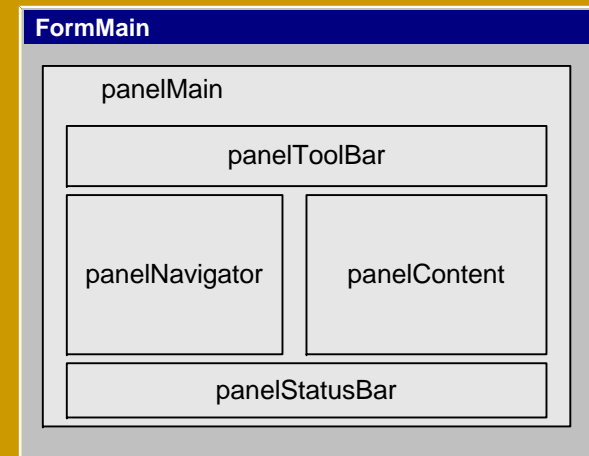
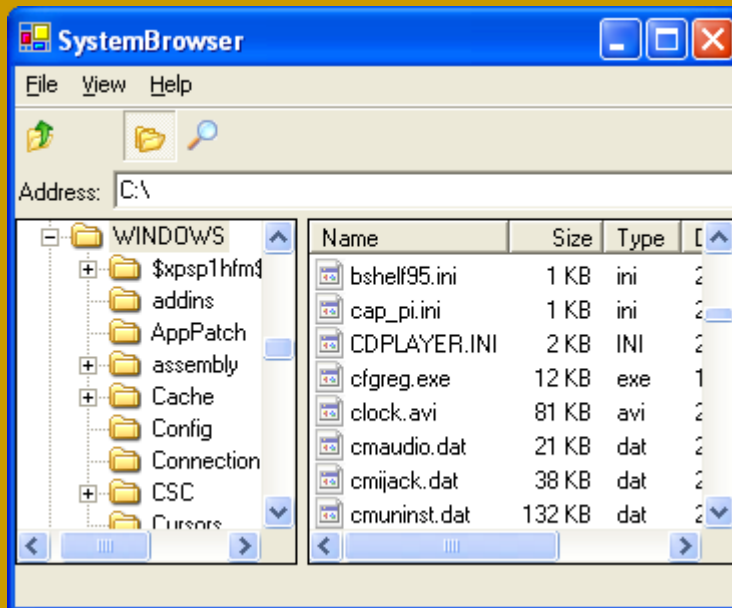


File Searcher

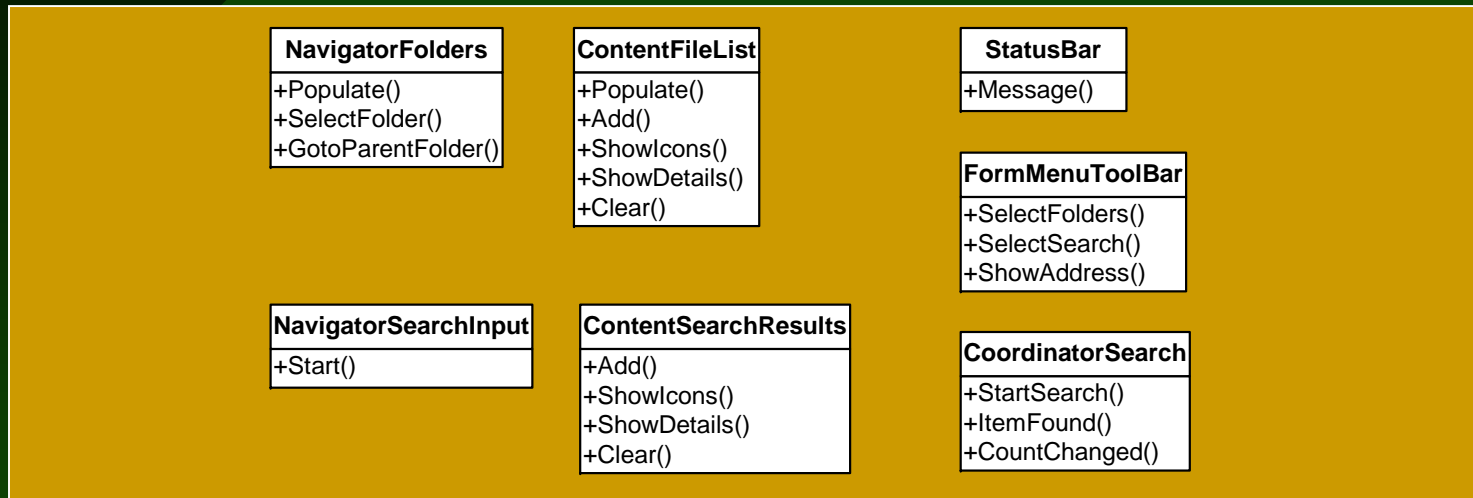
User Interface - File Searcher



User Interface Structure

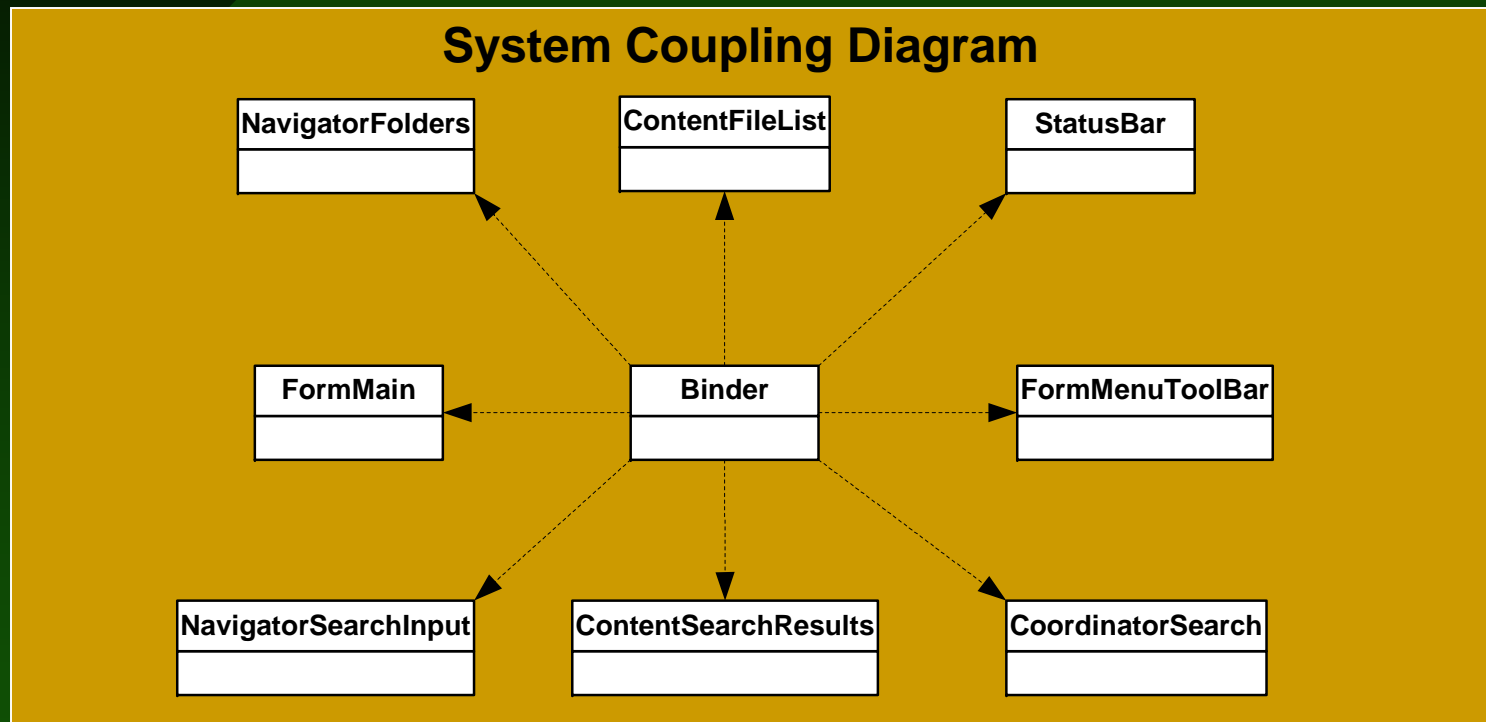


Class Diagram – Main Parts



- There are no relationships between the main classes, meaning there is no static coupling between them
- Objects interact using event notifications

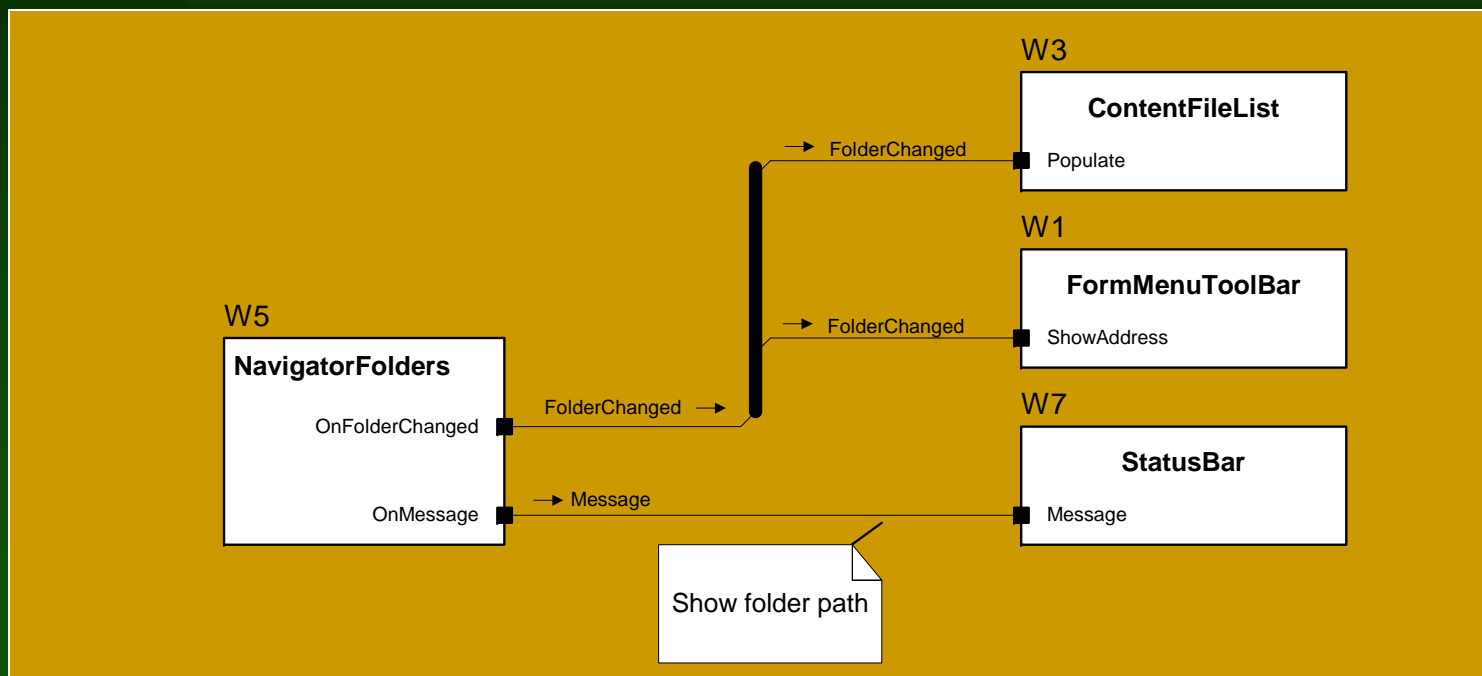
The Binder



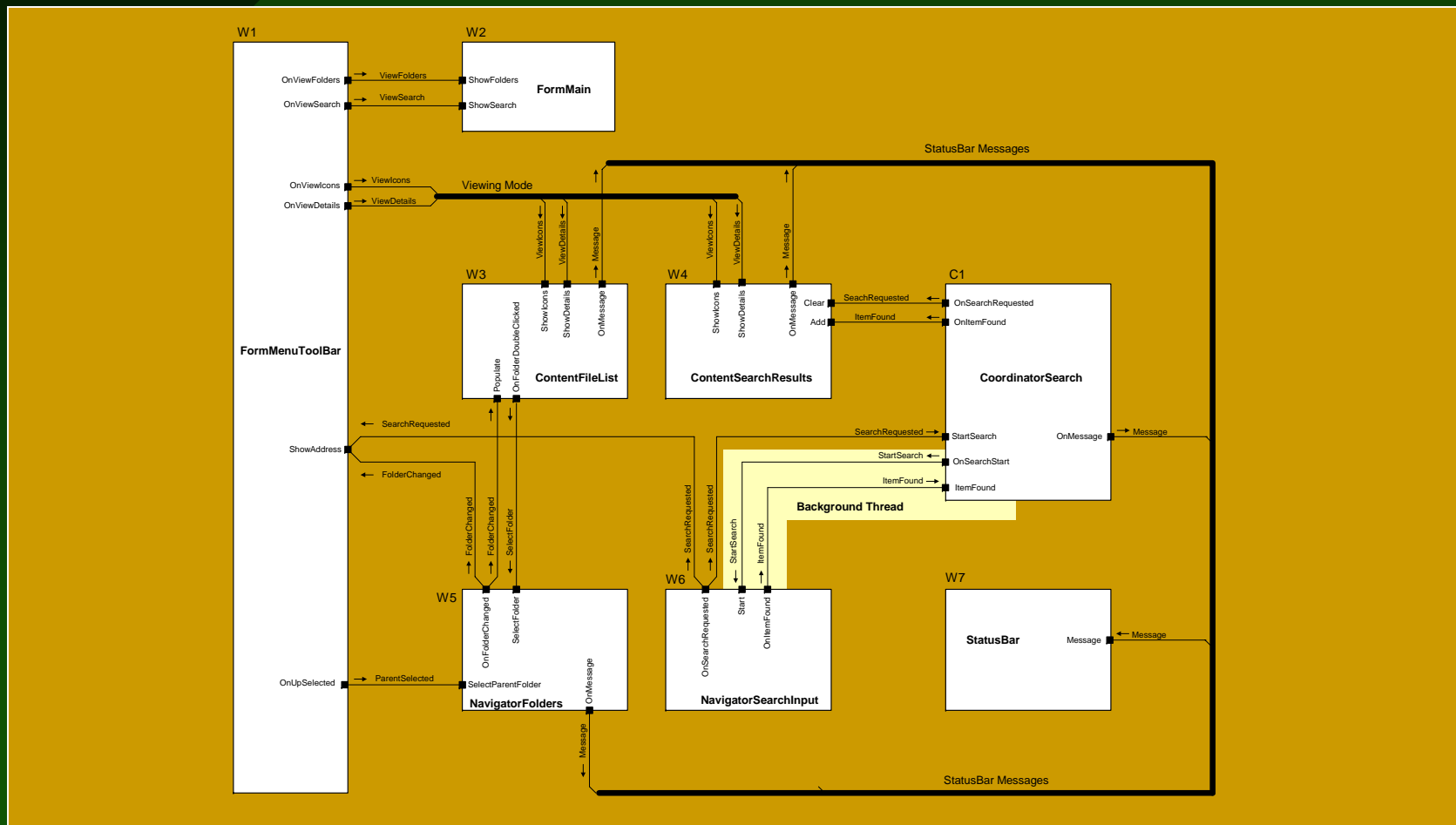
- The Binder is coupled to all the classes in the system

Signal Wiring Diagrams

- Use Case: User selects a folder in the Folders navigator



The Wiring Diagram as a blueprint of connectivity



Advantages of EBSs

- Most parts of a system are statically decoupled from the others
- Decoupled parts are easier to design, because they don't call other parts
- Decoupled parts are easier to develop and maintain, because they can be tested in isolation from the rest of the system
- Decoupled systems are easier to extend and evolve, since the main parts are not aware of the others