



Distributed Ground Systems

Breakout Session Summary

Session 8C

Donna Sellers



Breakout Session Goals

Definition:

- Ground Systems that provide flexible, secure, remote architectures for distributed telemetry (data), commanding, voice, video, and planning, with effective use of system automation.



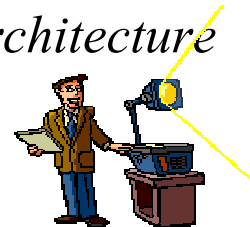
Goals:

- Identify effective use of custom components, design optimization, cost benefits, and system automation for distributed ground systems
- Look at lessons learned and effective use of COTS products with existing and future systems

Breakout Session Topics



- *Introduction* – Donna Sellers, NASA, Marshall Space Flight Center (MSFC)
- *Case for Deploying Complex Systems Utilizing Commodity Components* – R. Lee Pitts, Barry S. Bryant, Lockheed Martin Space Operations (Live ISS Data Demo)
- *Telescience Resource Kit* – Michelle Schneider, NASA, MSFC (PC Ground System Demo)
- *Utilization of Internet Protocol-Based Voice Systems in Remote Payload Operations* – Kelvin Nichols, Susan Best, Bob Bradford, NASA, MSFC (Live Voice Demo)
- *Awareness Requirements for Supporting Distributed Ground Control Expertise* – Michael Kantor, University of California, Irvine, Institute for Software Research (ISR)
- *Planning Systems for Distributed Operations* – Theresa Maxwell, NASA, MSFC
- *ISS Space-based Science Grid Briefing for the Ground Systems Architecture Workshop* – Clara Welch, Bob Bradford, NASA, MSFC
- Open Discussion/Closing Remarks



Case for Deploying Complex Systems Utilizing Commodity Components

R. Lee Pitts, Barry S. Bryant, Lockheed Martin Space Ops

- Focus was on the transition of a International Space Station (ISS) ground system from a client/server UNIX based system to a client/server system based on commodity priced and open system components
- Discussions on Motivation of Change
 - New projects such as ISS brought more, dispersed geographical users
 - Primary platforms (servers and workstations) reaching End-of-Life
 - Support for COTS products on the primary vendor dropping
 - High cost for replacement/maintenance
 - **BIG** budget constraints
- Initiatives included:
 - Moving from expensive UNIX workstations to lower cost Windows 2000 PC platforms, allowing for lower costs, user-friendly, and easy deployment
 - Redesigned or isolated expensive COTS products
 - Consolidating services or platforms into one single platform
 - Porting high costs UNIX server applications to low cost commodity based Linux systems

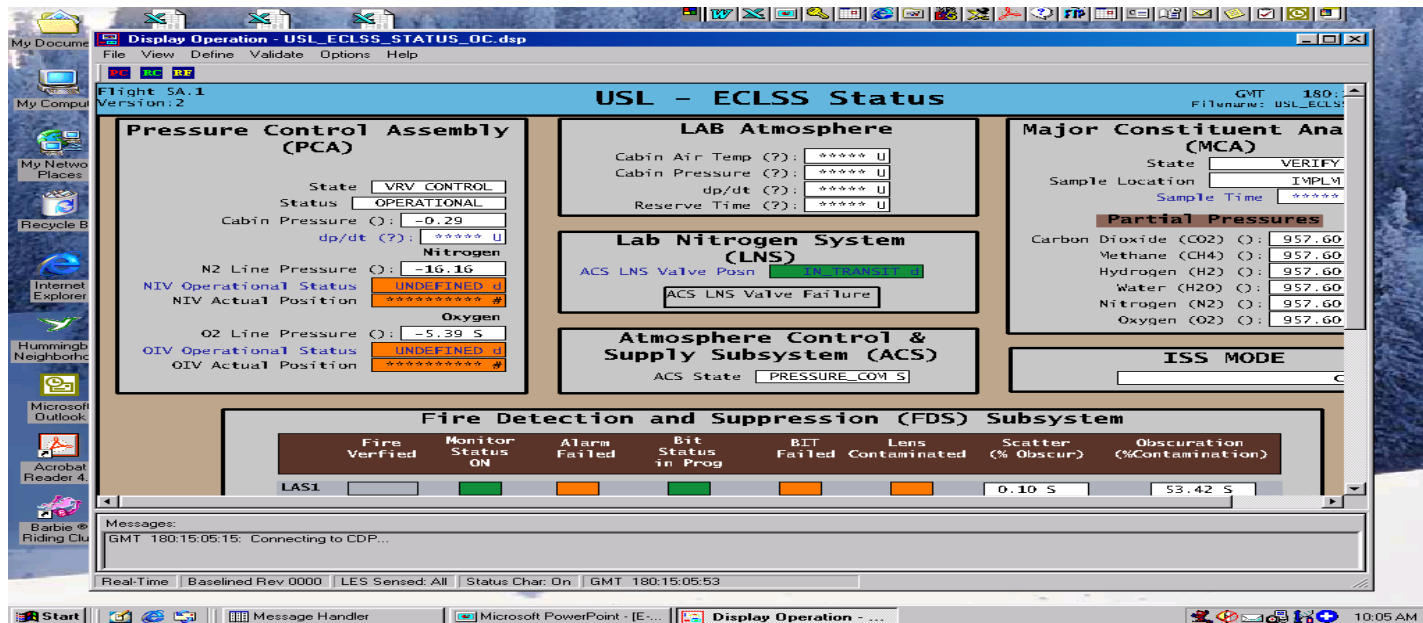


Case for Deploying Complex Systems Utilizing Commodity Components

R. Lee Pitts, Barry S. Bryant, Lockheed Martin Space Ops

- Summary and Conclusions

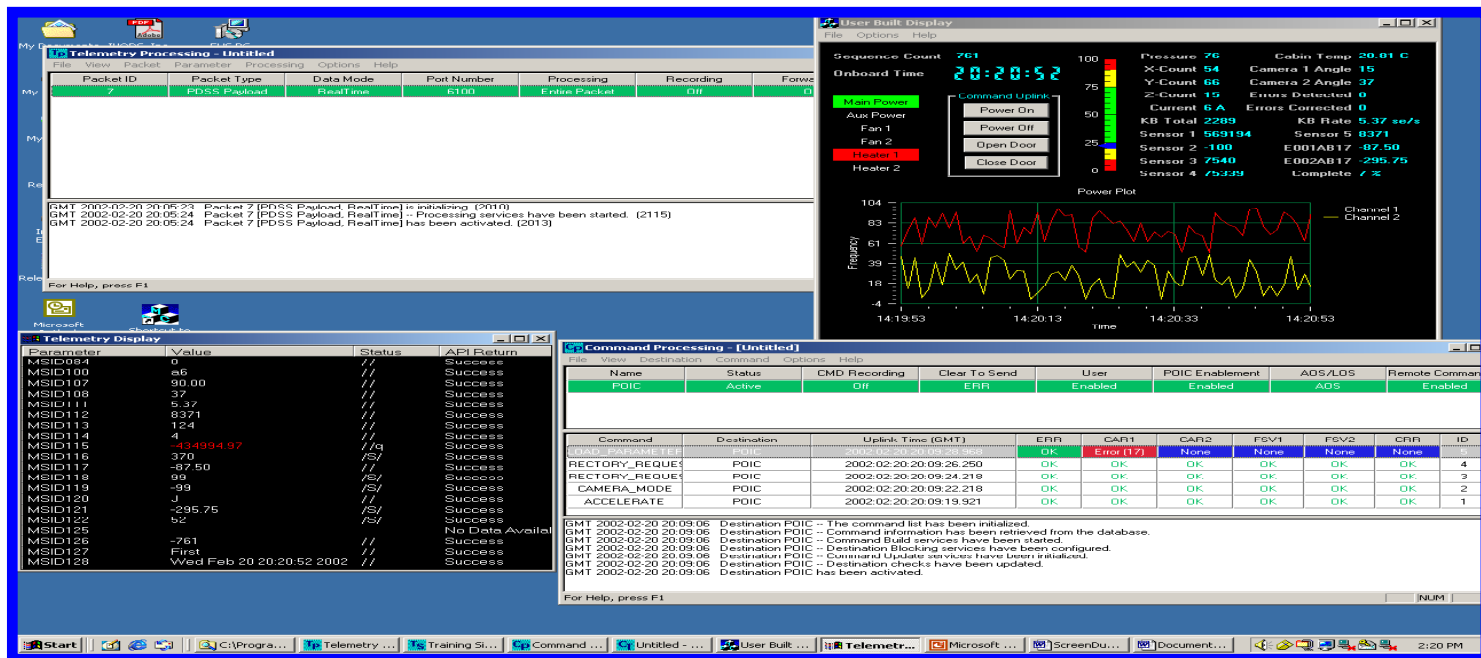
- Start with the high value targets and make changes incrementally
- Give commodity priced platforms more than a cursory look
- Stay current by utilizing technology insertion
- Reduce dependency on expensive, under-utilized COTS
- Looks for ways to migrate while maintaining access to legacy systems
- Don't try to do it all at once



Telescience Resource Kit

Michelle Schneider, NASA, MSFC

- Focus was on commodity PC-based ground system for Telemetry and Commanding functions
- Discussions on flexible ground systems that allowed remote users more control and local autonomy versus more centralized control
 - Application Programming Interface (API)
 - Use of COTS Tools
- Low cost solution for remote operations



The screenshot displays the Telescience Resource Kit software interface, which is a PC-based ground system for Telemetry and Commanding functions. The interface is divided into several windows:

- Telemetry Processing - Untitled:** A table showing packet processing details.
- User Built Display:** A control panel with various indicators and a power plot.
- Telemetry Display:** A table showing parameter values and status.
- Command Processing - Untitled:** A table showing command processing details.

Packet ID	Packet Type	Data Mode	Port Number	Processing	Recording	Forward
7	PDSS Payload	RealTime	E100	Entire Packet	Off	0

Parameter	Value	Status	API Return
MSID084	07	///	Success
MSID107	96	///	Success
MSID100	90.00	///	Success
MSID100	37	///	Success
MSID111	5.37	///	Success
MSID112	8371	///	Success
MSID113	124	///	Success
MSID114	4	///	Success
MSID115	-434894.97	///	Success
MSID116	370	///	Success
MSID117	-87.50	///	Success
MSID118	90	///	Success
MSID119	-99	///	Success
MSID120	J	///	Success
MSID121	-295.75	///	Success
MSID122	52	///	Success
MSID125		///	No Data Avail
MSID126	-761	///	Success
MSID127	First	///	Success
MSID128	Wed Feb 20 20:20:52 2002	///	Success

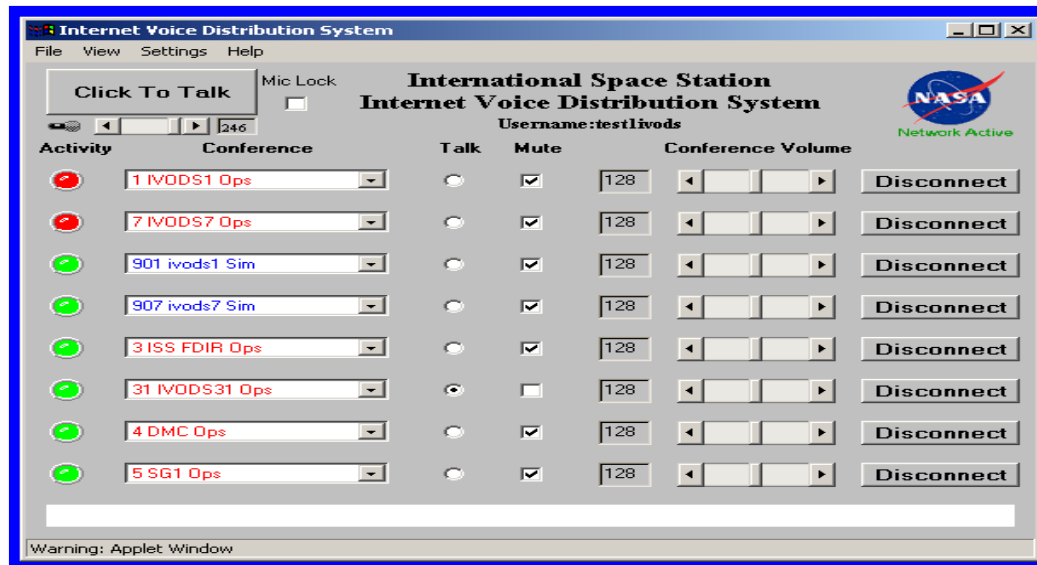
Name	Status	CMD Recording	Clear To Send	User	POIC Enablement	AOS/LDS	Remote Command
POIC	Active	Off	ERR	Enabled	Enabled	AOS	Enabled

Command	Destination	Uplink Time (GMT)	ERR	CAR1	CAR2	FSV1	FSV2	CRR	ID
CHAP_PARAMETER	POIC	2002-02-20 09:28:58	OK	OK	None	None	None	None	5
RECTORY_REQUEST	POIC	2002-02-20 09:24:250	OK	OK	OK	OK	OK	OK	4
CAMERA_MODE	POIC	2002-02-20 09:22:218	OK	OK	OK	OK	OK	OK	2
ACCELERATE	POIC	2002-02-20 09:19:921	OK	OK	OK	OK	OK	OK	1

Utilization of Internet Protocol-Based Voice Systems in Remote Payload Operations

Kelvin Nichols, Susan Best, Bob Bradford, NASA, MSFC

- Focus was on an innovative and cost-effective voice communications system
- Discussions on motivation for change to IP based distributed Voice systems
 - Expensive, end-of-life systems, with very high bandwidth costs
 - High number of remote users
 - Budget impacts
- IP based system offered low costs and easy deployment
- Suggestions for close customer integration, definition of roles and standards, and for modification of COTS for vendors if needed



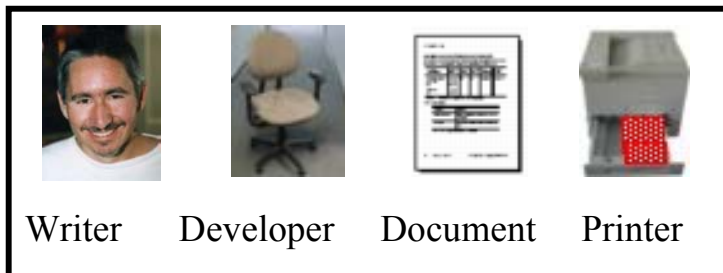
Awareness Requirements for Supporting Distributed Ground Control Expertise

Michael Kantor, University of California, Irvine, ISR

- Focus was on awareness for coordination and monitoring of ground control and distributed resources
- Discussed three awareness goals
 - Support awareness styles (example: Intrusive vs. peripheral)
 - Support diverse sources (example: people, servers)
 - Subscription refinement (example: list of objects)
- Discussed Creating Awareness through Subscription Services (CASS) infrastructure to enhance coordination:
 - Among developers building ground control systems
 - Among ground control staff, software and hardware components
 - Between ground control and external expertise

Awareness Tools

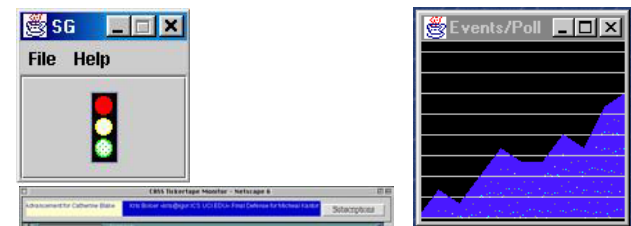
Complex: CASS-Portholes



Mobile Awareness



Simple desktop widgets



Planning Systems for Distributed Operations

Theresa Maxwell, NASA, MSFC

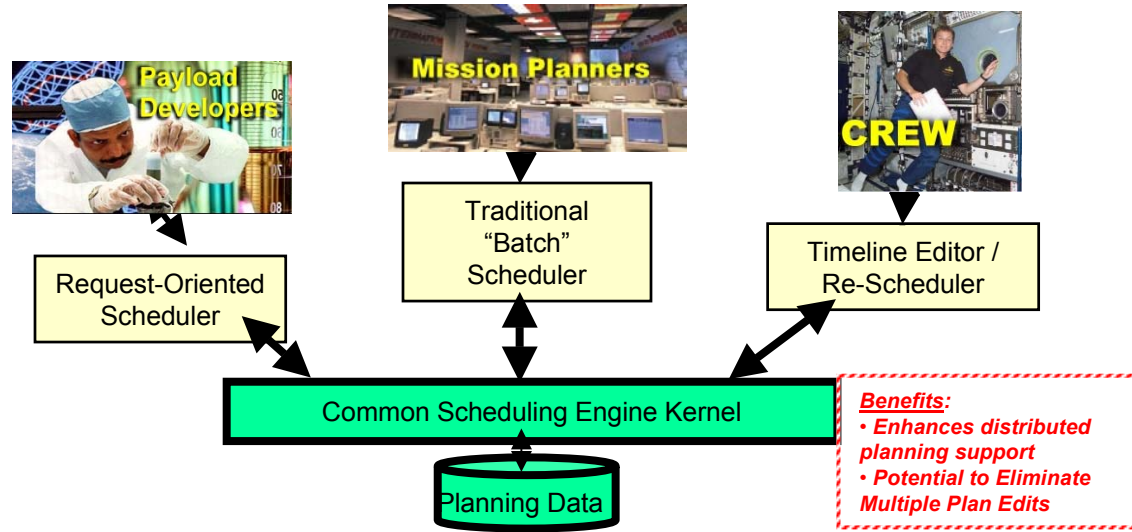
- Focus was on a planning system evolution from a centralized to a more distributed planning system
- Described the major functions of an ISS distributed planning system that provides user requirements collection, activity planning and scheduling, data system routing and configuration, and planning products
- Major goals were to enhance support for distributed planning, reduce operating costs, and to provide robust planning capabilities
- Discussed request-oriented scheduling engines and next generation planning systems



Planning Systems for Distributed Operations

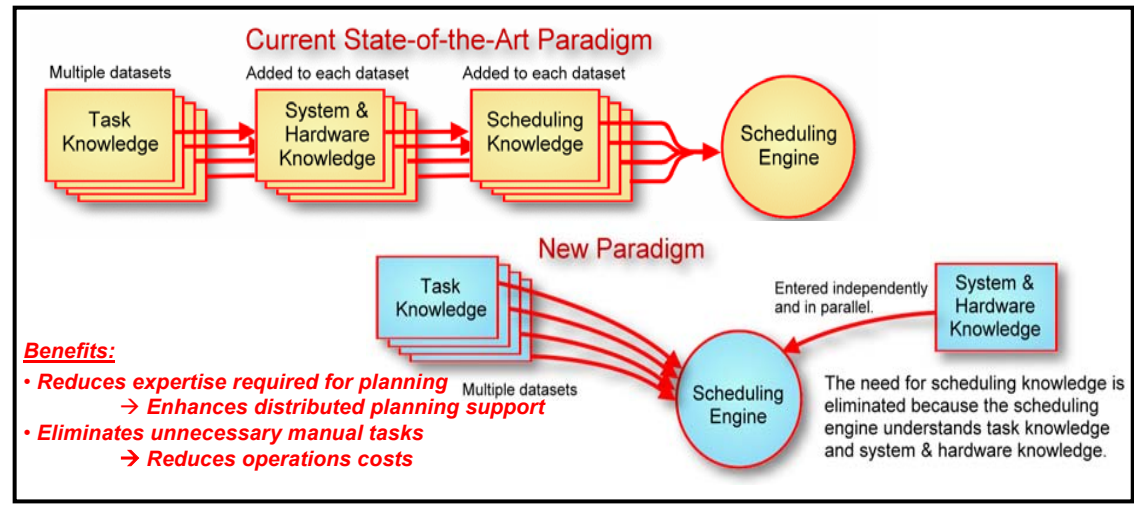
Theresa Maxwell, NASA, MSFC

Strategy: Develop core capabilities which can be packaged in various ways to distribute planning functions, based on individual expertise and need



Strategy: Enable more automated planning through:

- Maximally expressive modeling of requirements and constraints
- Robust scheduling engine which can handle the expressive models



ISS Space-based Science Grid Briefing for the Ground Systems Architecture Workshop

Clara Welch, Bob Bradford, NASA, MSFC



- Focus was on Grid infrastructure as a new innovative solution for fast reliable secure computing
- Discussed the definition Grid and suitable technology
 - what is (Decentralized *virtual organizations* requiring distinct services)
 - what's not (Applications that run quickly and easily on one machine)
- Also, discussed the increase and simplified access needs for distributed ground services as well as the need for security that can be available through Grid technology
- Provided a detailed prototype and draft proposal for Grid technology and its related uses for distributed ground systems



Session Summary/Conclusion

- Session covered a wide range of distributed ground systems topics to include large, complex component systems; small, more versatile component systems; awareness within ground systems, and secure distributed system automation
- Presenters showed and utilized effective use of custom components, design optimization, cost benefits, and system automation for distributed ground systems, providing both lessons learned and effective use of COTS products with existing and future systems
- Large range of interaction between demos, questions, and participants

